EASTERN UNIVERSITY, SRI LANKA

SECOND EXAMINATION IN SCIENCE 1994/95 & 95/96

(August/September'97)

MT205 & 208 - MATHEMATICAL METHODS & NUMERICAL ANALYSIS

Time: Two hours.

Answer only four questions selecting two from each section.

SECTION A

MATHEMATICAL METHODS

1. (a) i. Write the transformation equations for the following tensors.

$$A_{jk}^{i}$$
, B_{l}^{ijk} , C_{mn} .
ii. If $\overline{A}_{r}^{p} = \frac{\partial \overline{x}^{p}}{\partial x^{q}} \frac{\partial x^{s}}{\partial \overline{x}^{r}} A_{s}^{q}$, then prove that $A_{s}^{q} = \frac{\partial x^{q}}{\partial \overline{x}^{p}} \frac{\partial \overline{x}^{r}}{\partial x^{s}} \overline{A}_{r}^{p}$.

- (b) If $A(p,q,r)B_r^{qs}=C_p^s$, where B_r^{qs} is an arbitrary tensor and C_p^s a tensor, then prove that A(p,q,r) is a tensor.
- (c) Find the covariant and contravariant components of a tensor in cylindrical coordinates (ρ, ϕ, z) if its covariant components in rectangular co-ordinates are $xy, 2y z^2, xz$.
- 2. (a) Define the following:
 - i. Christoffel symbols of first and second kind,
 - ii. Geodesics.



(b) Prove the following:

$$i. [pq, r] = [qp, r],$$

ii.
$$\Gamma_{pq}^s = \Gamma_{qq}^s$$
,

iii.
$$[pq, r] = g_{rs} \Gamma^s_{pq}$$
.

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- (c) Find the second kind of the Christoffel symbol in spherical co-ordinates (r, θ, ϕ) .
- i. Explain the term "Covariant derivative" as applied to a tensor of type 3. (a.) A_{bc}^{a} .
 - ii. Write the covariant derivative with respect to x^q of each of the following tensors.

$$A_l^{jk}, \quad A_{klm}^j, \quad A_{lmn}^{jk}.$$

(b) With the usual notations, prove the following:

i.
$$\frac{\partial g_{pq}}{\partial x^m} = [pm, q] + [qm, p];$$

ii.
$$\frac{\partial g^{pq}}{\partial x^m} = -g^{pn} \Gamma^q_{mn} - g^{qn} \Gamma^p_{mn}$$
.

Deduce that the covariant derivatives of the tensors $|g_{jk}, g^{jk}, \delta_k^j|$ are zero.

(c) Using the covariant derivative of metric tensor, prove that

$$\Gamma_{ca}^{e} = \frac{1}{2} g^{eb} \left[\partial_{c}(g_{ab}) + \partial_{a}(g_{cb}) - \partial_{b}(g_{ca}) \right],$$

semi "rate of convergence" of direct iteration used to find the

where
$$\partial_i = \frac{\partial}{\partial x^i}$$
.

SECTION B,

NUMERICAL ANALYSIS

4. (a) Use induction on r to show that the Horner algorithm

fundamental Lagrange polynomials lock, le

$$k_0 = a_n,$$

 $k_r = b k_{r-1} + a_{n-1} \text{ for } r = 1, 2, \dots, n,$

generates a sequence (k_r) that satisfies

$$k_r = a_n b^r + a_{n-1}b^{r-1} + \cdots + a_{n-r} \text{ for } r = 0, 1, \dots n.$$

Show also that

$$a_n x^n + a_{n-1} x^{n-1} + \ldots + a_0 = (x-b)(k_0 x^{n-1} + k_1 x^{n-2} + \cdots + k_{n-1}) + k_n.$$

Hence find the following: In divided difference formula to approximate y 0.05)

- i. the quotient polynomial and remainder when $p(x) = 3x^5 + 5x^4 + 8x^2 + 7x + 4$ is devided by x + 2;
 - ii. the Taylor series of p(x) about the point x = -2.
- (b) Explain what is meant by
 - i. fixed point representation,
 - ii. floating point representation.

For base 16, round the number $\frac{\pi}{2} = (1.921FB54...)_{16}$ to

- i. 5 places in fixed point,
- ii. 5 digits in floating point.

(In base 16, A = 10, B = 11, C = 12, D = 13, E = 14, F = 15.)

- 5. (a) Define the term "rate of convergence" of direct iteration used to find the roots of any non-linear equation.
 - (b) Let $f:[a,b] \longrightarrow \Re$ be a continuous and differentiable function on [a,b]. State the Newton-Raphson iteration to find the roots of the equation f(x)=0.
 - (c) Show that the order of convergence of the Newton-Raphson method is two.
 - (d) Use the Newton-Raphson method to find the real positive root of the equation $f(x) = x^3 x^2 x 3 = 0$ accurate to two decimal places. [Hint: Estimate f(2) and f(3)]

- (e) Which cases will the Newton-Raphson method fail?
- 6. (a) Let $f:[a,b] \longrightarrow \Re$ and let x_0, x_1, \ldots, x_n be distinct points in [a,b]. Define the fundamental Lagrange polynomials $l_0, l_1, l_2, \ldots, l_n$ for these interpolation points and show that the polynomial P given by

$$P(x) = \sum_{j=0}^{n} f(x_j) l_j(x),$$

the Lagrange introolation polynomial, interpolates f at $x_0, x_1, x_2, \ldots, x_n$.

Show also that this is the unique polynomial of degree atmost n that interpolates f at these points.

Find the lagrange interpolation polynomial for $f(x) = \frac{1}{x}$ using the distinct points $x_0 = 2$, $x_1 = 2.5$, $x_2 = 4$.

(b) Use the Newton interpolation divided difference formula to approximate f(0.05) from the following data.

Х	0.0	0.2	0.4	0.6
f(x)	15.0	21.0	30.0	51.0

(c) Find the area, in the first quadrant, bounded by the curve y = (x - 1)(x + 5)(9 - x) and x-axis by using composite Simson rule with step-size h = 1.