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## EASTERN UNIVERSITY, SRI LANKA

## SECOND EXAMINATION IN SCIENCES - 2003/2004

## SECOND SEMESTER

(JUNE/JULY 2005)

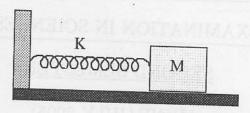
REPEAT

PH 206 WAVES AND VIBRATIONS

Time: 01 hour.

Answer ALL Questions

1. Consider a horizontal coiled spring carring a mass M in one end and the other end to a wall as shown in the figure. Assume that the system is placed in a frictionless and the spring is stretched at a distance x from its equilibrium position. Den equation of motion for the system and show that it is a simple harmonic motion.



A horizontal coiled spring is found to be stretched 0.10 m from its equlibrium po when a force of 4 N acts on it. Then a body of mass 1.6 Kg is attached to one end spring and is pulled 0.12 m along a horizontal frictionless table from the equil position. The body is then released and executes S.H.M. Find

the force constant of the spring (i)

- the force exerted by the spring on 1.6 Kg body just before it is released (ii)
- period of oscillation after release (iii)

(iv) amplitude of motion

- the velocity, acceleration, kinetic energy and potential energy of the (v) when it is moved half-way from its initial position towards the cen the motion.
- the total energy of the oscillating system (vi)
- the equation of motion of the body. (vii)

2. The equation of motion of a driven harmonic oscillator is

$$m x + b x + kx = F_0 \cos \omega t$$

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where b is the resistance factor and k is the spring factor.

(a). Show that it possesses a steady state solution of the form

$$x = A \cos(\omega t - \delta),$$

where

$$A = \frac{\frac{F_0}{m}}{\sqrt{\left(\omega_0^2 - \omega^2\right)^2 + \left(\frac{\omega}{\tau}\right)^2}}$$

and

$$\delta = \tan^{-1} \left( \frac{\frac{\omega}{\tau}}{\left(\omega_0^2 - \omega^2\right)} \right)$$

Here  $\frac{b}{m} = \frac{1}{\tau}$  and  $\frac{b}{m} = \omega_0^2$ .

Hence deduce an expression for the velocity amplitude  $x_0$ .

(b). Show that for a particular frequency and for given driving force the velocity amplitude depends on mass, resistance factor and spring factor for the cases  $\omega >> \omega_0$ ,  $\omega = \omega_0$  and  $\omega << \omega_0$  respectively.